



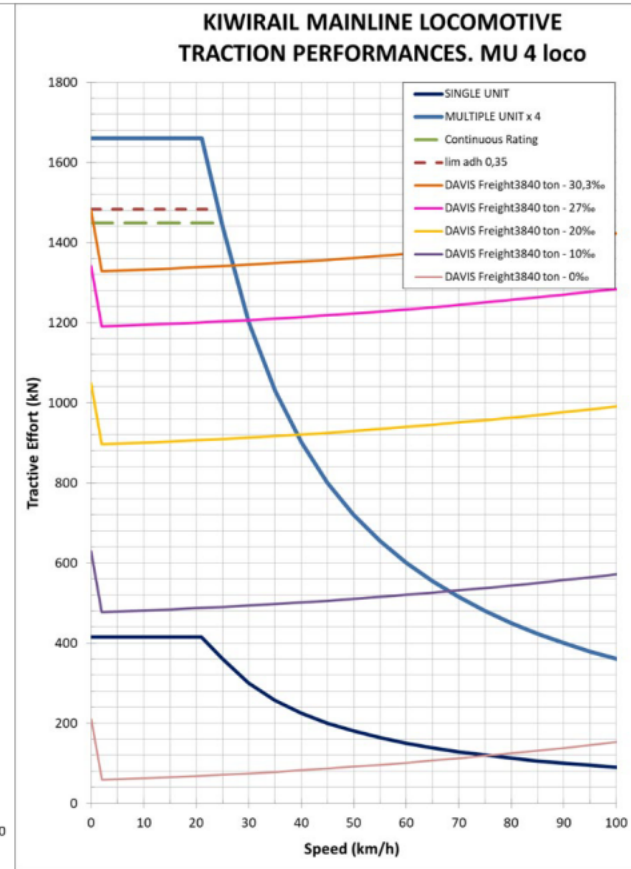
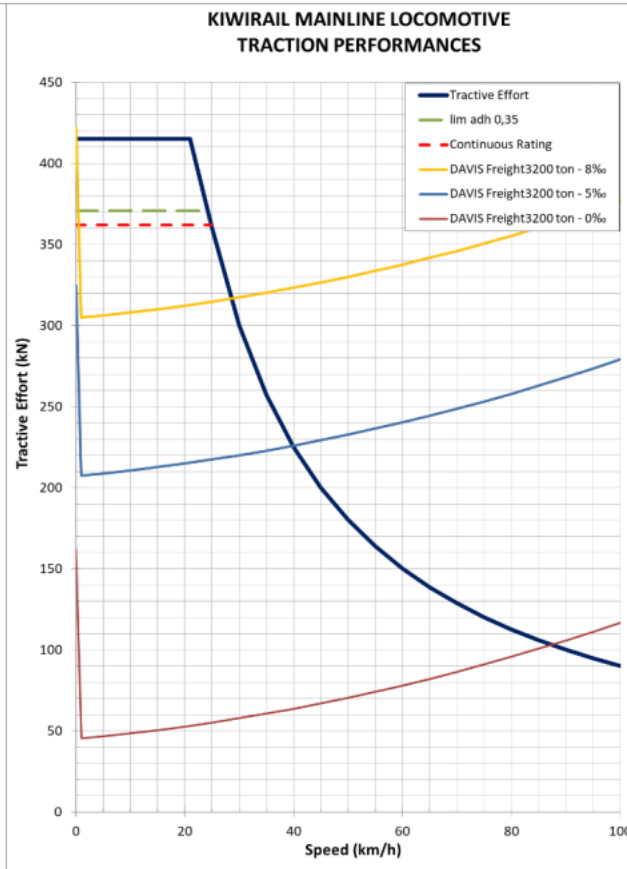
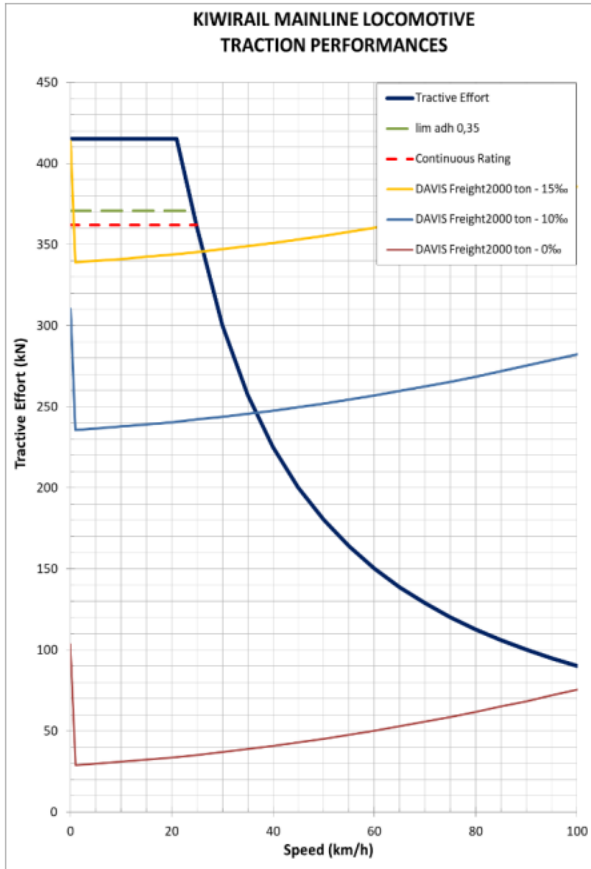
KIWI RAIL: EVOLUTION FOR NEW ZEALAND / AUSTRALIEN

Dr. Ansgar Brockmeyer, Darmstadt 09/2024

STADLER

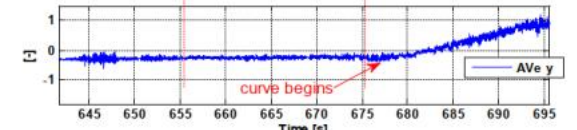
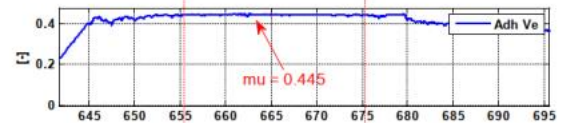
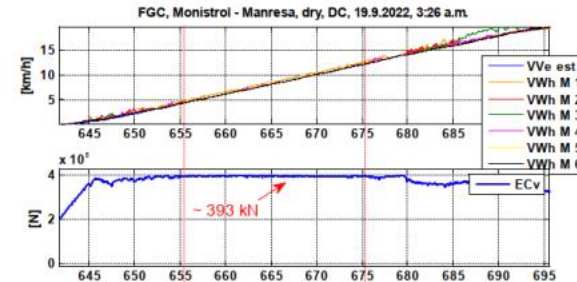
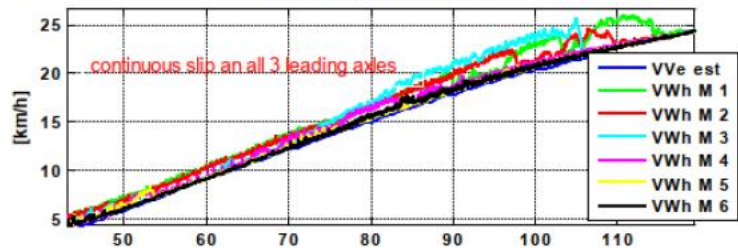
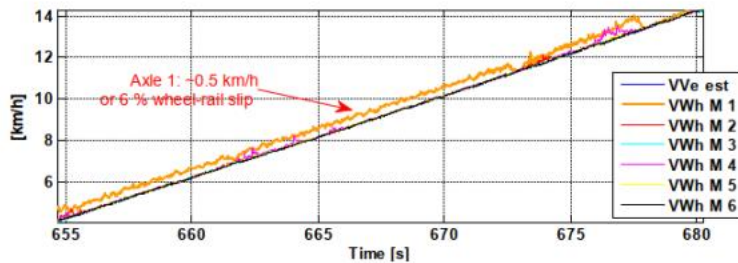
THE PLATFORM

LOW AXLE LOAD_HEAVY HAUL



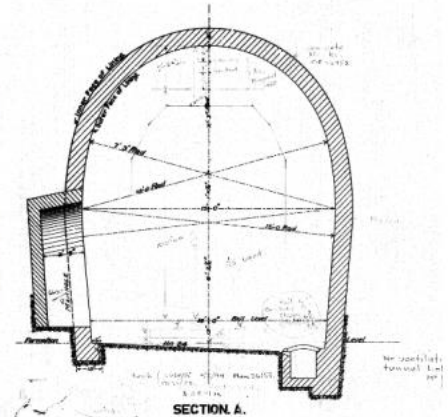
THE PLATFORM

NEW DEVELOPMENTS: TRACTION CONTROL

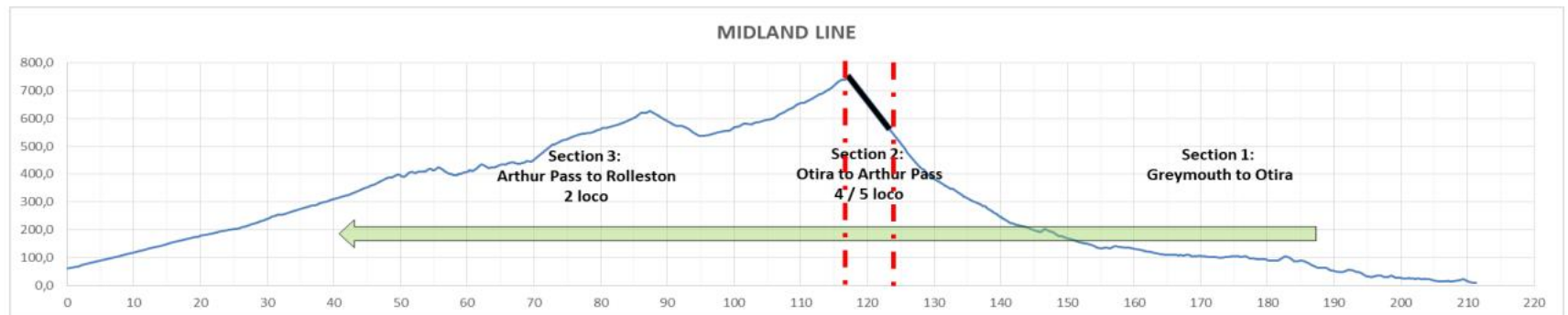


THE PLATFORM

OTIRA TUNNEL



8.5 km long on a 30,3 ‰ gradient
5.18 m high
4.57 m wide



THE PLATFORM

OTIRA TUNNEL

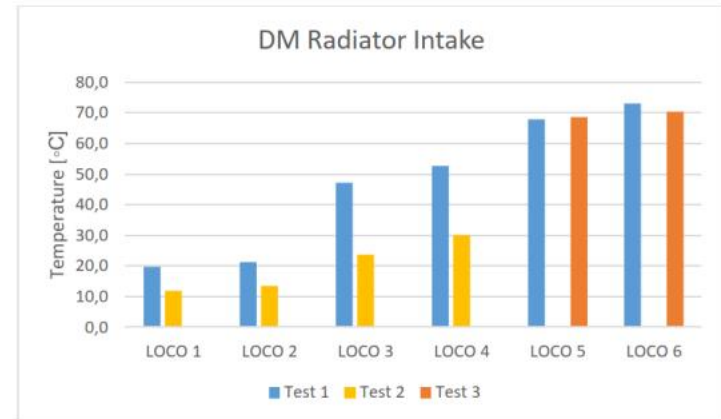
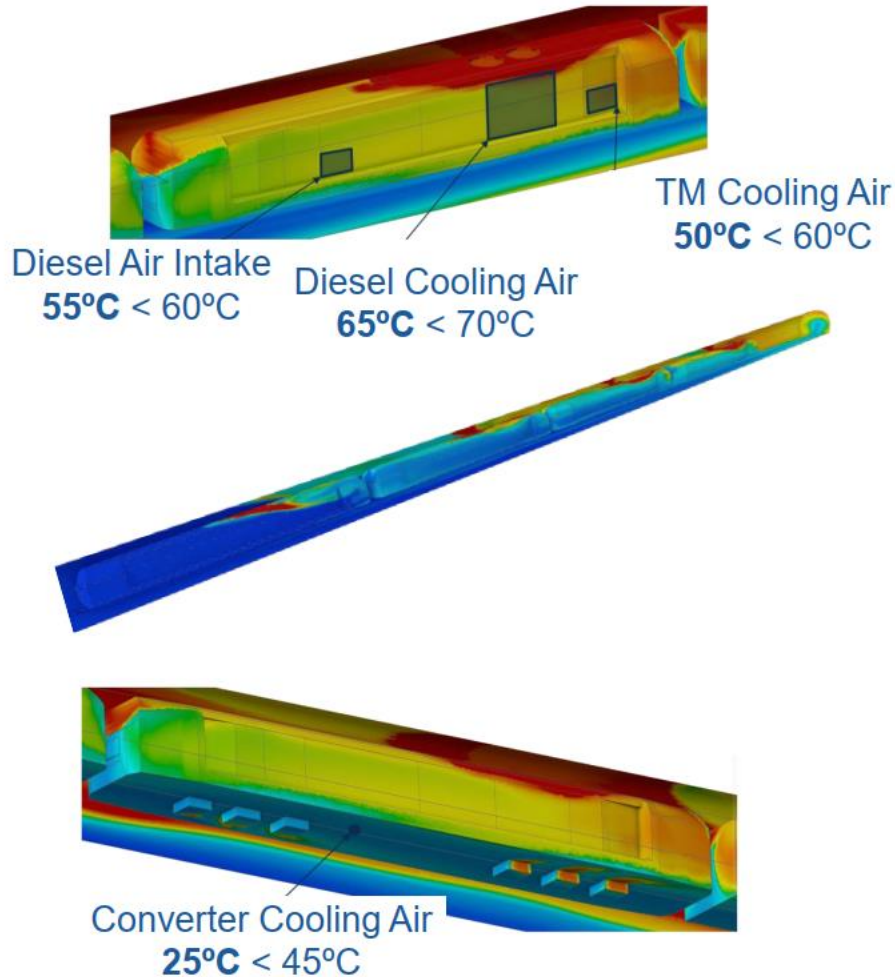


Figure 3-18: Estimated temperature for the DM Radiator Intake

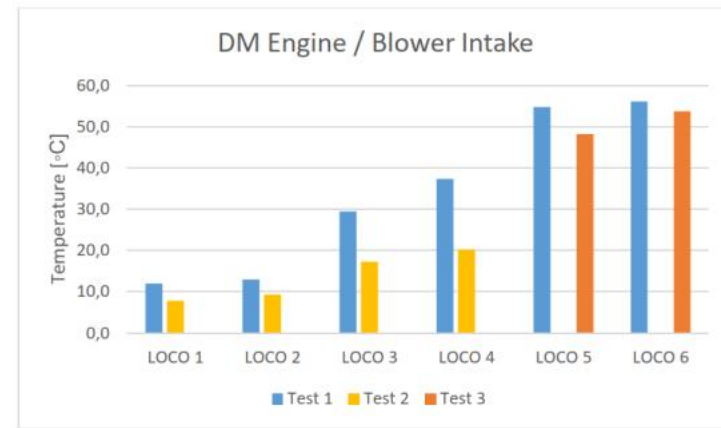
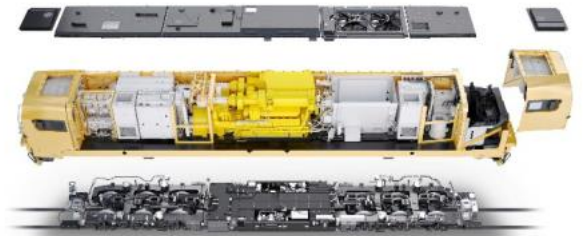


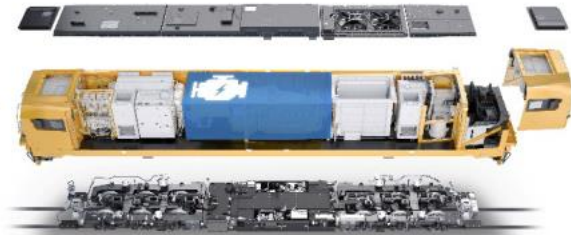
Figure 3-19: Estimated temperature for the DM Engine/Blower Intake

THE PLATFORM “GREEN” OPTIONS

Stage V Diesel



3,000 KW
18 tons/axle



Stage V Diesel
1,800 KW
16 tons/axle

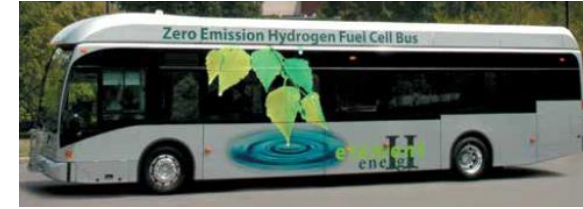


Hybrid
Stage V Diesel
1,000 KW Diesel
600 KWh Battery



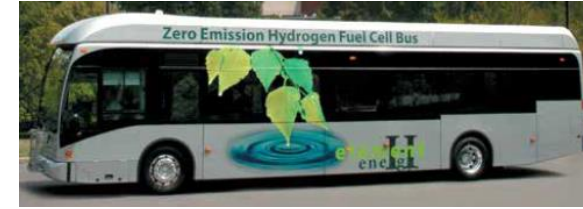
Battery only
2,000 KWh Battery

Battle of the HD EVs With John Hayes

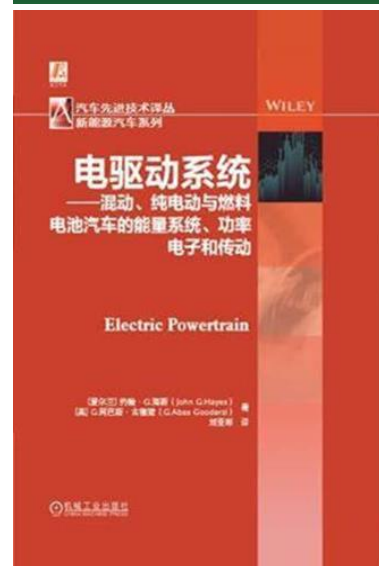
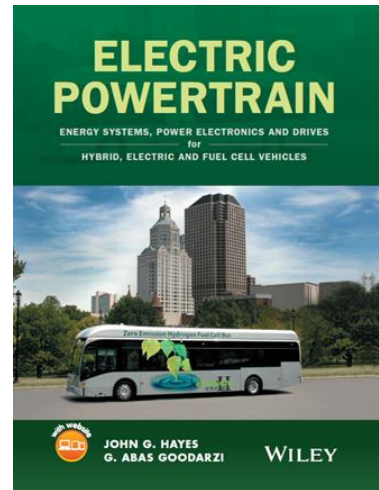
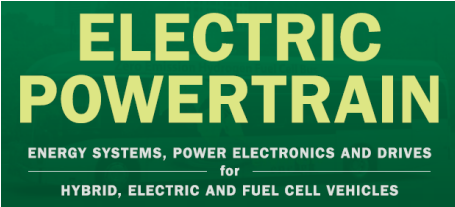


Images courtesy of Tesla, Mercedes, Timoney & Stadler

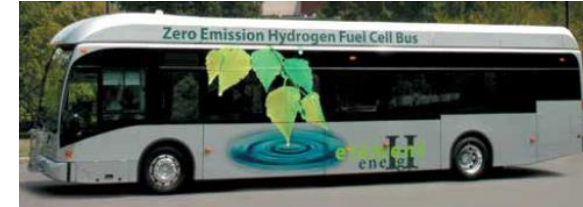
Background



- Dedicated **university textbook** and **industry reference** on electric vehicles.
- **Chinese** language edition by China Machine Press in 2021.
- Presents a **structured university teaching stream** from **introductory undergraduate** to **postgraduate**.
- Introduces and **holistically integrates** the key **EV powertrain** technologies.
- Features lots of **examples, problems** and **assignments**.
- **2nd Edition** under development.

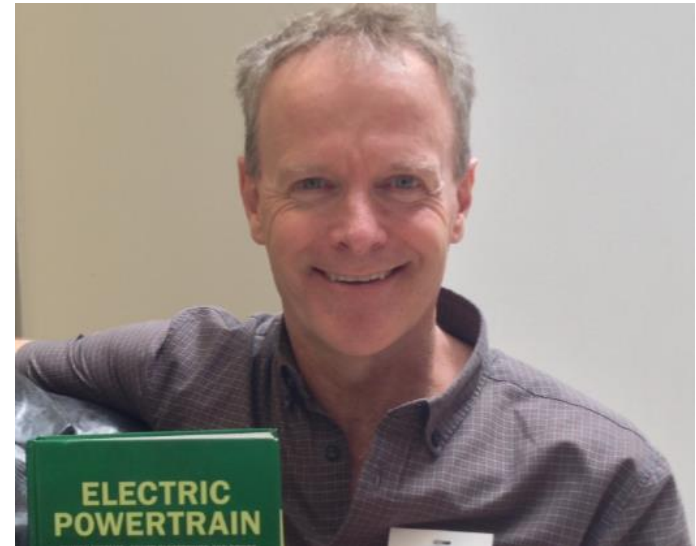


Biographies



John G. Hayes, PhD, MSEE, MBA

- Senior Lecturer at **University College Cork**.
- **Energy systems, power and machines.**
- Worked for **ten years at General Motors** developing power systems for the **GM EV1**, the first modern production EV.

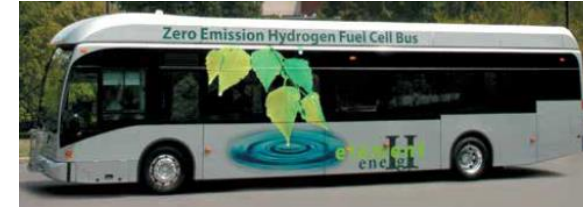


G. Abas Goodarzi, PhD, P.E.

- **Chief Executive Officer of Magmotor**
- **Former CEO and President of US Hybrid Corp.**
- **Technical Director for the GM EV1.**
- Designed various **EV, HEV, and FCEV** powertrain systems for **light, medium, and heavy-duty, on-road, off-road, and special-purpose vehicles.**



Tesla Truck Video



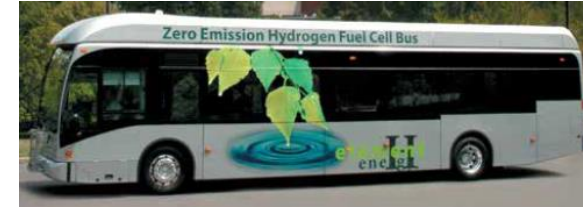
Elon Musk of Tesla Inc. introduced the new Tesla truck in November 2017, as documented in the following Youtube video.

<https://chargedevs.com/newswire/tesla-semi-hits-the-highway-with-a-bang/>

In the following slides we will estimate the battery size based on information presented in the video.

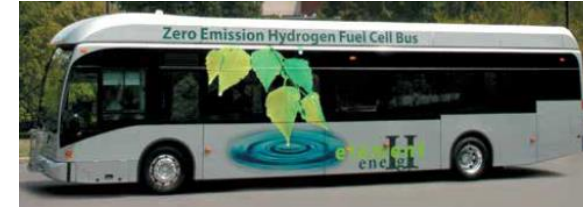
First watch the video.

Tesla Truck – Key learnings



- Maximum gross weight for tractor-trailer **80,000 lbs.**
- Range is **500 miles** at an average speed of **60 mph.**
- The drag co-efficient C_D is **0.36.**
- **0 to 60 mph** in 5 seconds empty
- **0 to 60 mph** in 20 seconds full.
- **65 mph** fully loaded up a **5% grade.**
- **Recharge to 400 miles** of range in **30 minutes.**
- There are **4 motors** – one on each of the rear wheels.
- **Battery life of 1,000,000 miles.**

The Problem



Determine the battery size in kWh and kg if the specific energy SE is 0.17 kWh/kg.

Assumptions:

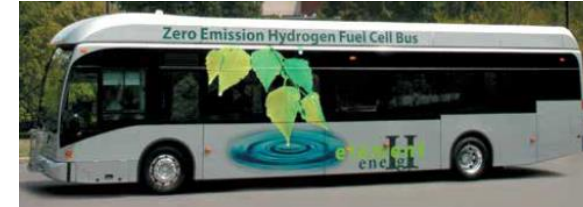
Frontal area $A = 9 \text{ m}^2$,

Rolling resistance $C_R = 0.006$,

Auxiliary load $P_{aux} = 2 \text{ kW}$.

G. Paterlini et al., Rolling Resistance Validation Final Report, Minnesota Dept. of Trans. 2015.

Solution



$$\text{Battery Power} = P_b = \frac{P_D + P_R}{\eta_{pt}} + P_{aux} = \frac{0.5 \rho C_D A v^3 + C_R m g v}{\eta_{pt}} + P_{aux}$$

$$= \frac{37.5 + 57.3}{0.85} + 2000 = 74.7 \text{ kW}$$

$$\text{Fuel Consumption} = \frac{P_b}{v} = \frac{74.7 \text{ kW}}{1.609 \times 60 \text{ km/h}} = 1.15 \frac{\text{kWh}}{\text{km}}$$

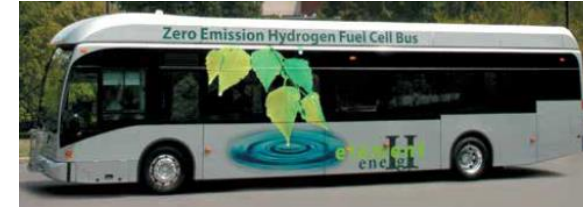
$$\text{Battery Size} = E_b = FC \times \text{Range} = 1.15 \frac{\text{kWh}}{\text{km}} \times 800 \text{ km}$$

$$= 920 \text{ kWh}$$

$$\text{Battery Mass} = m_b = \frac{E_b}{SE} = \frac{920 \text{ kWh}}{0.17 \text{ kWh/kg}}$$

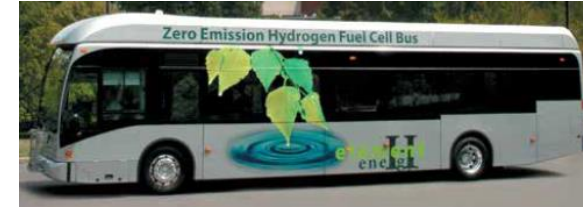
$$= 5,400 \text{ kg}$$

Reference Websites



- <https://chargedevs.com/newswire/tesla-semi-hits-the-highway-with-a-bang/>
- <https://hub.mercedes-benz-trucks.com/int/en/trucks/eactros-600.html>
- <https://www.timoneygroup.com/heavy-duty-electric-vehicle-solutions>
- <https://stadlerrail.com/en/>

HD EVs Vehicle & Battery



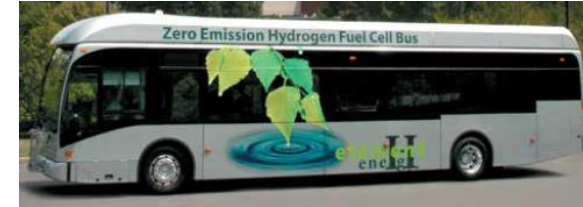
	Tesla Semi	Mercedes eActros 600 Semi	Timoney Off-road	Stadler Locomotive
Mass	36,290 kg (80,000 lb)	40,000 kg (88,000 lb)	9,000 kg per axle	2,000,000 kg
Range (Fuel Consumption)	800 km (500 miles) @ 96.5 kph (60 mph)	500 km (1.2 kWh/km)		5,000 L
Battery (useable/gross)	960 kWh (≈ 6,000 kg)	600/621 kWh (3 x 207 kWh packs)		2,000 kWh
Chemistry	?	LFP		LTO (NMC)
Voltage	850 V (250 to 300 cells in series?)			1.5-2 kV (3-level) IGBT
Battery Warranty	1,609,000 km (1,000,000 miles)	6 years/720,000 km/1,800 charging cycles		10 years
Service Life		10 years/1,200,000 km/3,000 charging cycles		30 years, 300,000 km/year

HD EVs Power & Vehicle



	Tesla Semi	Mercedes eActros 600 Semi	Timoney Off-road	Stadler Locomotive
Charging	400 miles in 30 min. $\approx 1,000$ kW	20 % to 80 % in 30 min. ≈ 720 kW		
Continuous Power		400 kW		3 MW
Peak Power		600 kW	200 kW per axle	
Speeds		Four		100 km/h
Challenges	104.6 kph (65 mph) up a 5 % grade		60 % grade, 30 % side slope	6 % grade
Drag Coefficient	0.36			
Rolling Resistance	0.6 %			0.1 + %

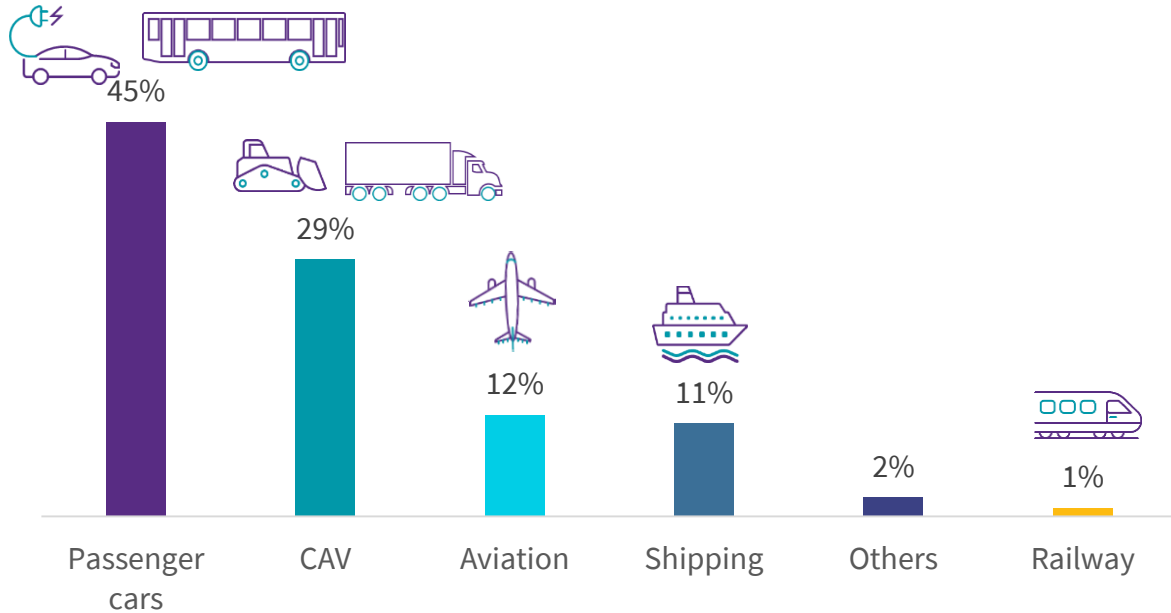
Questions



- Battery packs... LTO vs. NMC vs. LFP?
- Machines- EESG+Induction, IPM?
- Semiconductors: IGBT vs. SiC MOSFET
- Modelling: torque vectoring, speed vectoring

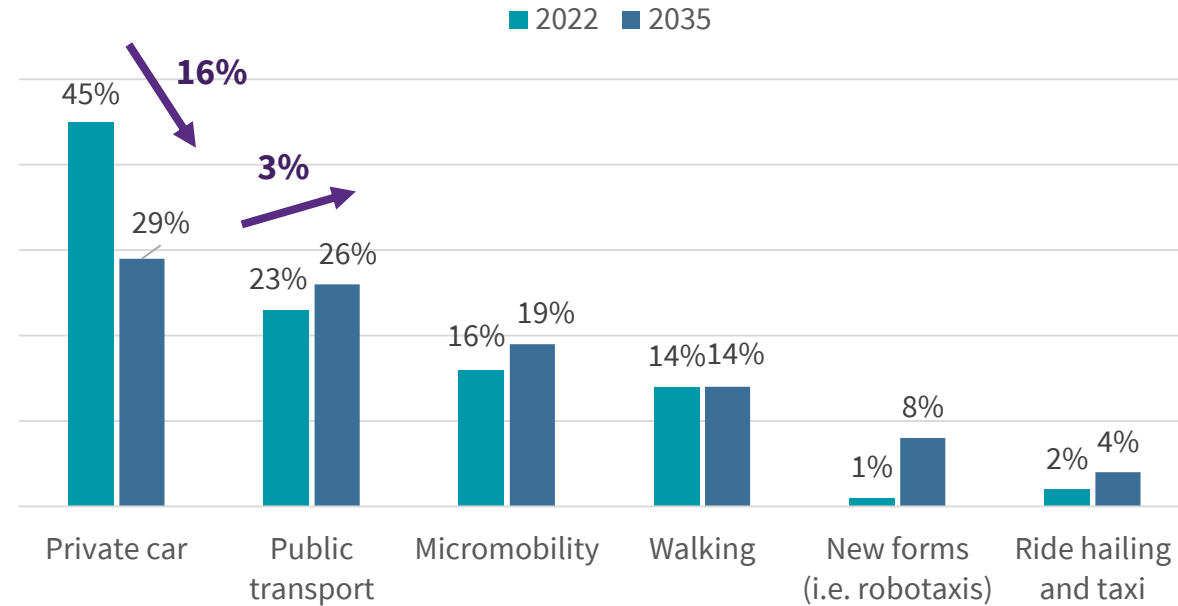
FACTORS DRIVING INDUSTRIAL E-MOBILITY

Global CO₂ emissions



Source: NESTE: Towards sustainable mobility / April 2023

Usage of mobility by population

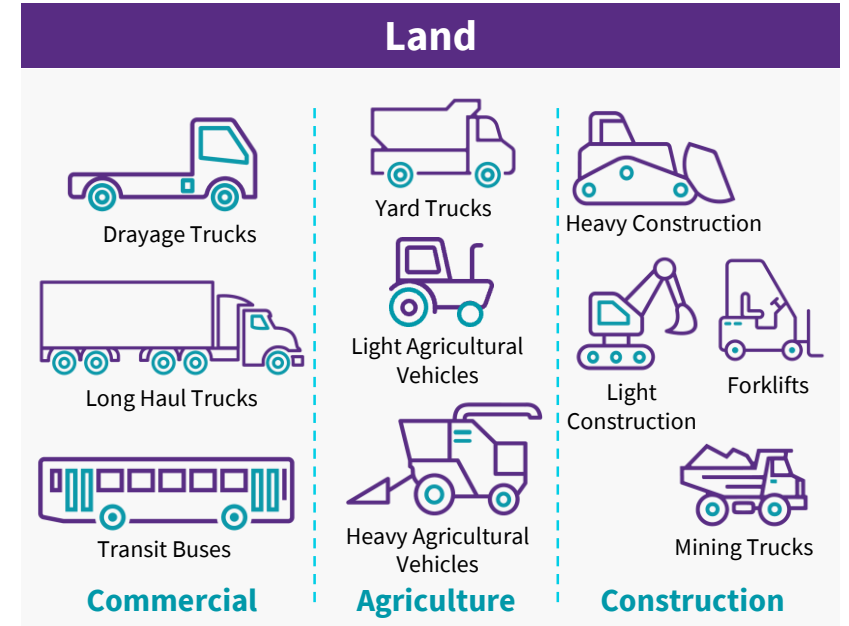
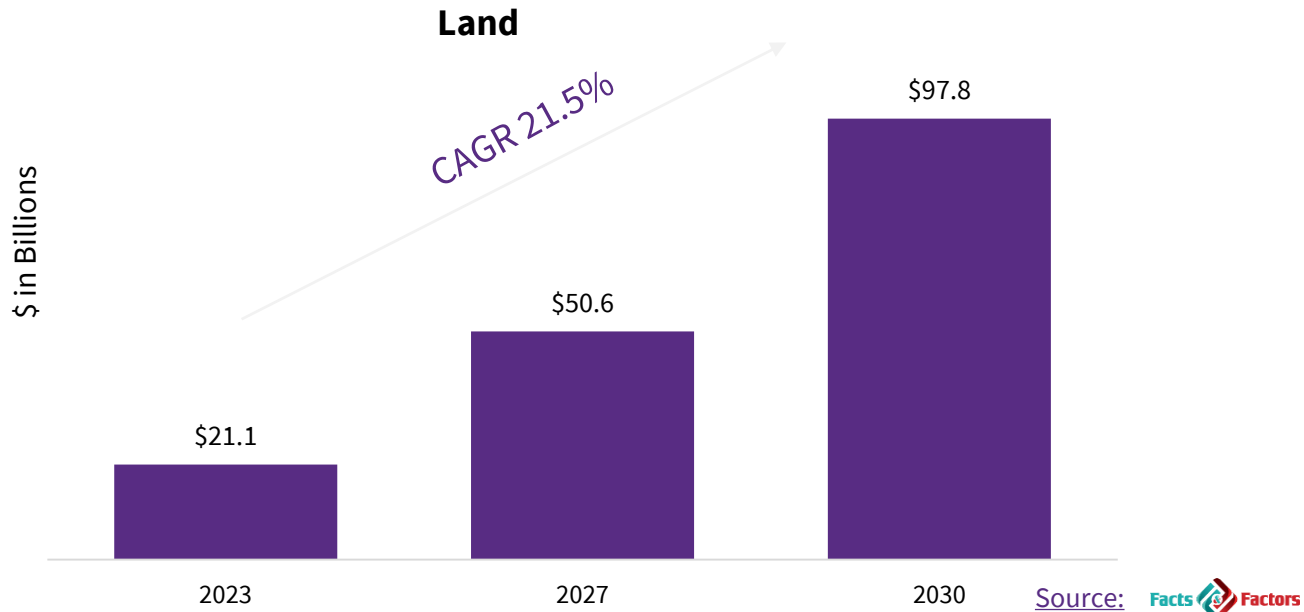


Source: McKinsey Center for future Mobility April 2023

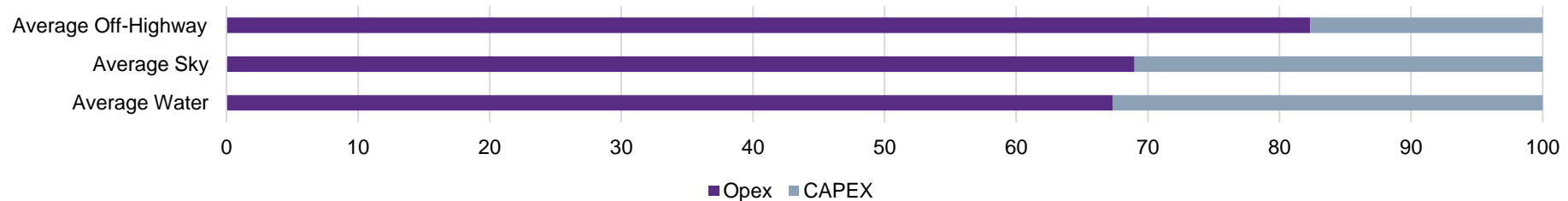
24% of global emissions come from transportation
(worldwide = ~30Gt)

Global population will reach ~8.9B by 2035, growing by more than >10% as today

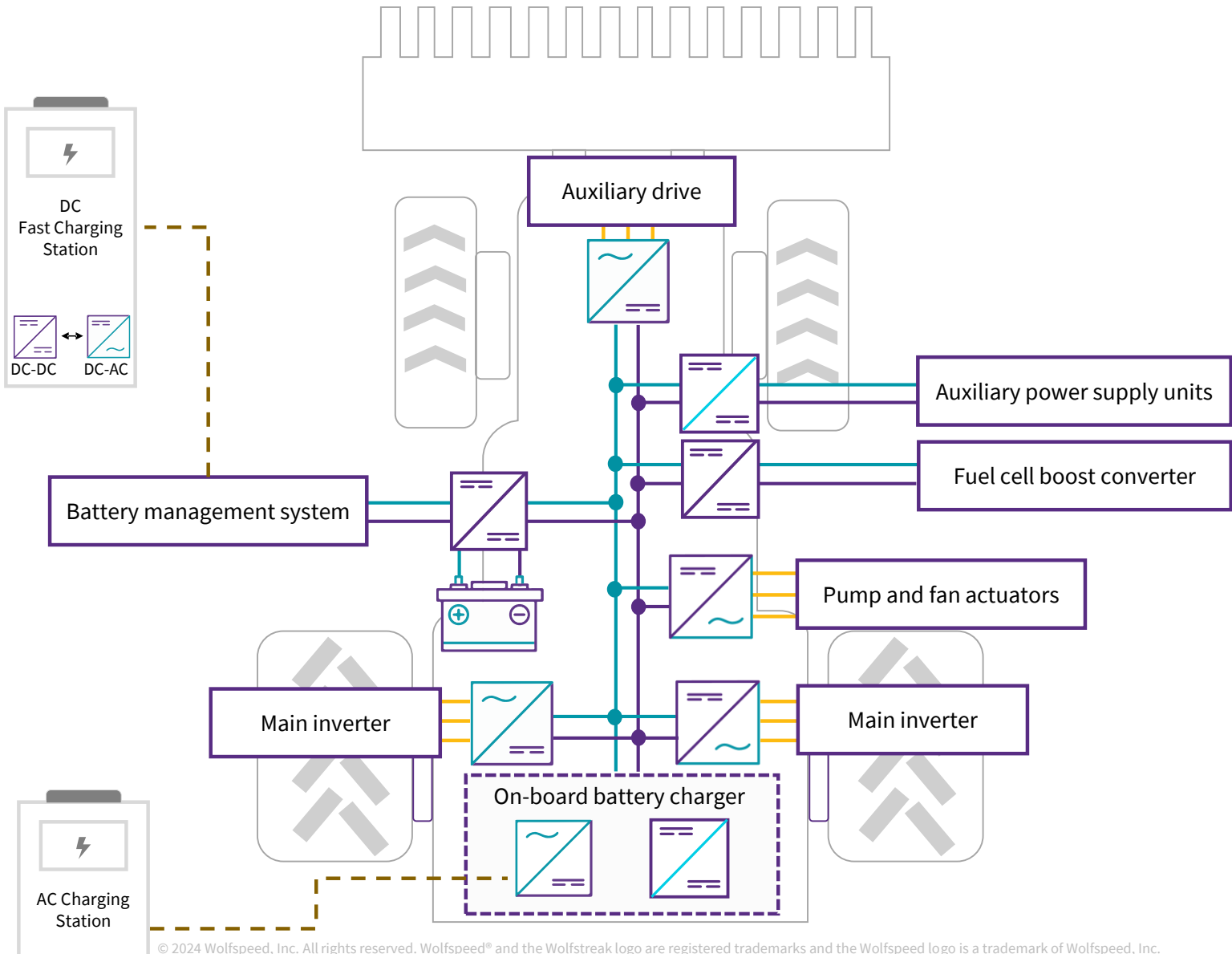
MARKET GROWTH FOR ELECTRIFICATION



Average Total Cost of Ownership of Electrification (TCO)



LAND APPLICATIONS - ELECTRONIC SYSTEM OVERVIEW



Technical specifications

- Main Inverter: **75 – 500+ kW**
- Auxiliary Drive: **10 – 30 kW**
- Auxiliary Electronics: **200 W – 1kW**
- Switching Frequency: **30+ kHz**

Topology technical highlights

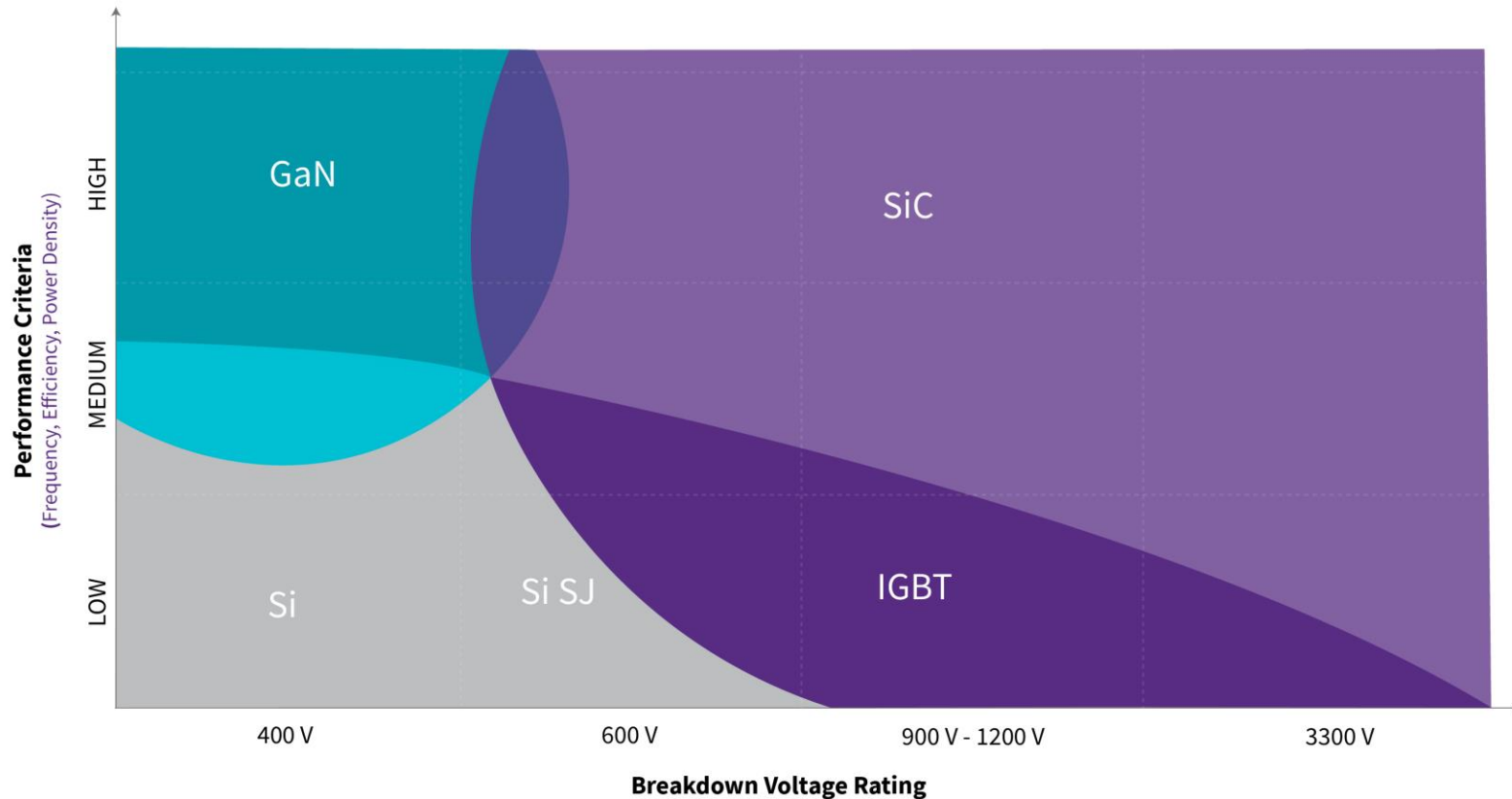
- Low component count
- Wide soft-switching range available
- High conversion efficiency (>95%)
- Galvanic isolation
- Bi-directional power flow

Key Features

- Combination of trolley and battery power reduces CO₂ emissions/fossil fuel consumption, ventilation requirements
- Estimated energy recovery as high as 65% in off-road mining dump trucks depending on load, grade, speed
- Low maintenance, long lifetime, reduced operating costs
- High efficiency, high power, bidirectional inverter

POWER TECHNOLOGY COMPARISON

Typical performance criteria verses breakdown voltage rating



Si, GaN, and SiC compete at the 650 V range

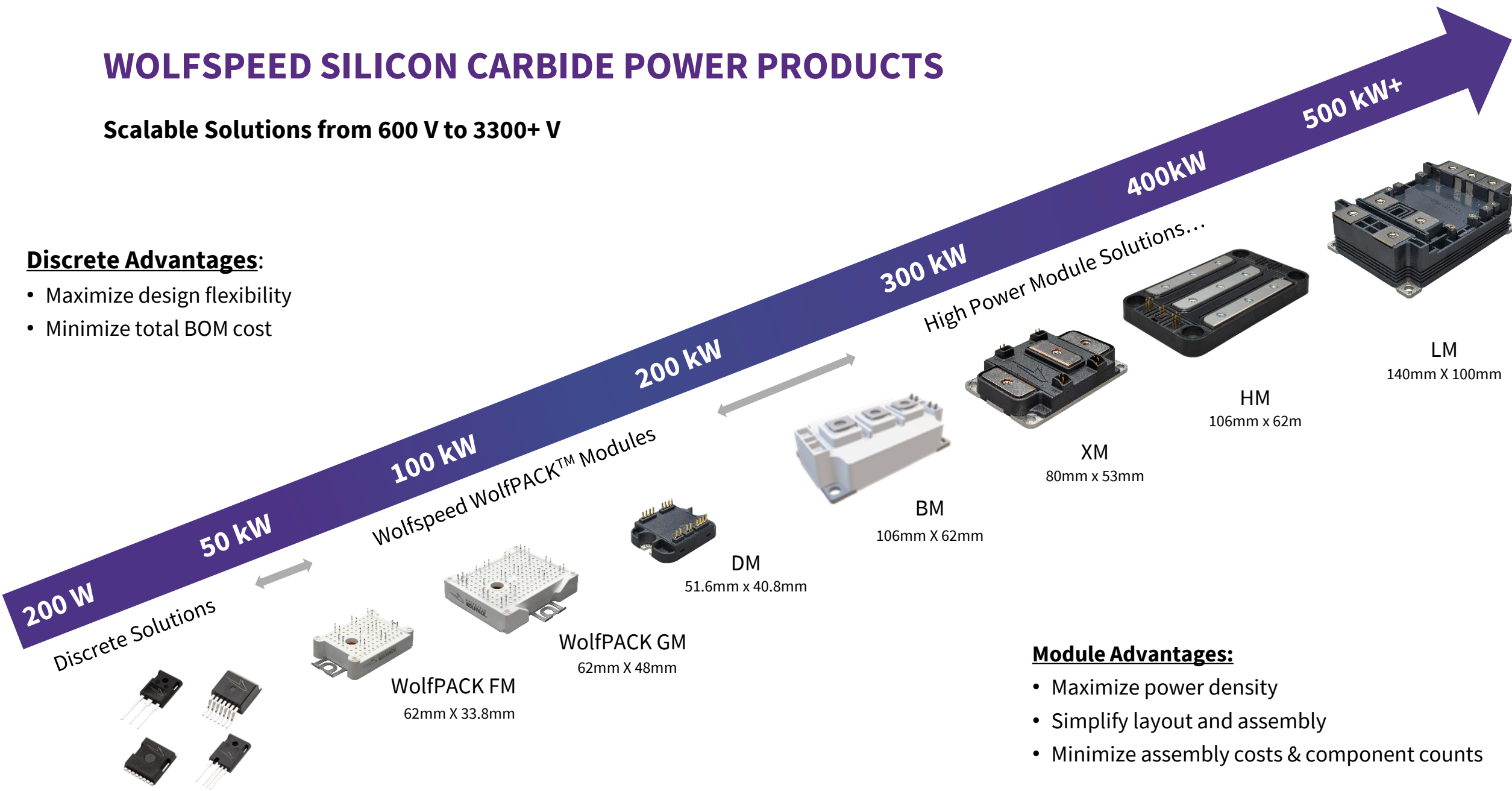
- **Silicon carbide is the best-in-class technology for power applications from 650 V – 3300 V+**
 - Baseline performance brings lower conduction losses and improved thermal efficiency
 - Enables system size reduction
 - Reduces system cost
- **Silicon does the job – “adequately” – up to 650 V**
 - MOSFETs: 5 V to ~900 V
 - IGBTs: 650 V to mid voltage
 - Not suitable for high-speed switching
- **GaN is touted for 40 V to 600 V**
 - High switching frequency, high power density
 - Lower current & power:
 - 40 V to 200 V at low current
 - 600 V in low to medium current (5A to 50A max)

WOLFSPEED SILICON CARBIDE POWER PRODUCTS

Scalable Solutions from 600 V to 3300+ V

Discrete Advantages:

- Maximize design flexibility
- Minimize total BOM cost



Module Advantages:

- Maximize power density
- Simplify layout and assembly
- Minimize assembly costs & component counts

CASE STUDY: REGENERATIVE BRAKING OF PURE ELECTRIC MINING TRUCKS

Premise and Objective

- Mining industry is exceptionally energy intensive: earth moving, hauling, sorting
- Diesel mining dump trucks can consume up to 34 liters/km in operation
- Decarbonization of supply chain for clean energy technologies via regenerative braking of dump truck for material hauling
- Kinetic energy recovered by inverter motor drive charges battery for use when trolley power is unavailable

Key Features

- Combination of trolley and battery power reduces CO₂ emissions/fossil fuel consumption, ventilation requirements
- Estimated energy recovery as high as 65% in off-road mining dump trucks depending on load, grade, speed
- Low maintenance, long lifetime, reduced operating costs
- High efficiency, high power, bidirectional inverter

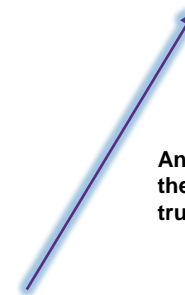
The battery re-charges when the brakes are applied during descent



The battery powers the mining truck during loading / unloading



An overhead power line recharges the battery and powers the mining truck during ascent



Modeling and Simulation of Electric Powertrains for Heavy-Duty Applications

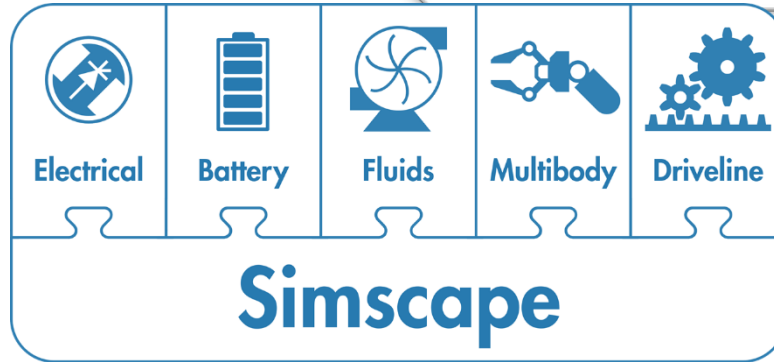
Sabin Carpiuc, PhD

Principal Physical Modeling Engineer

MathWorks

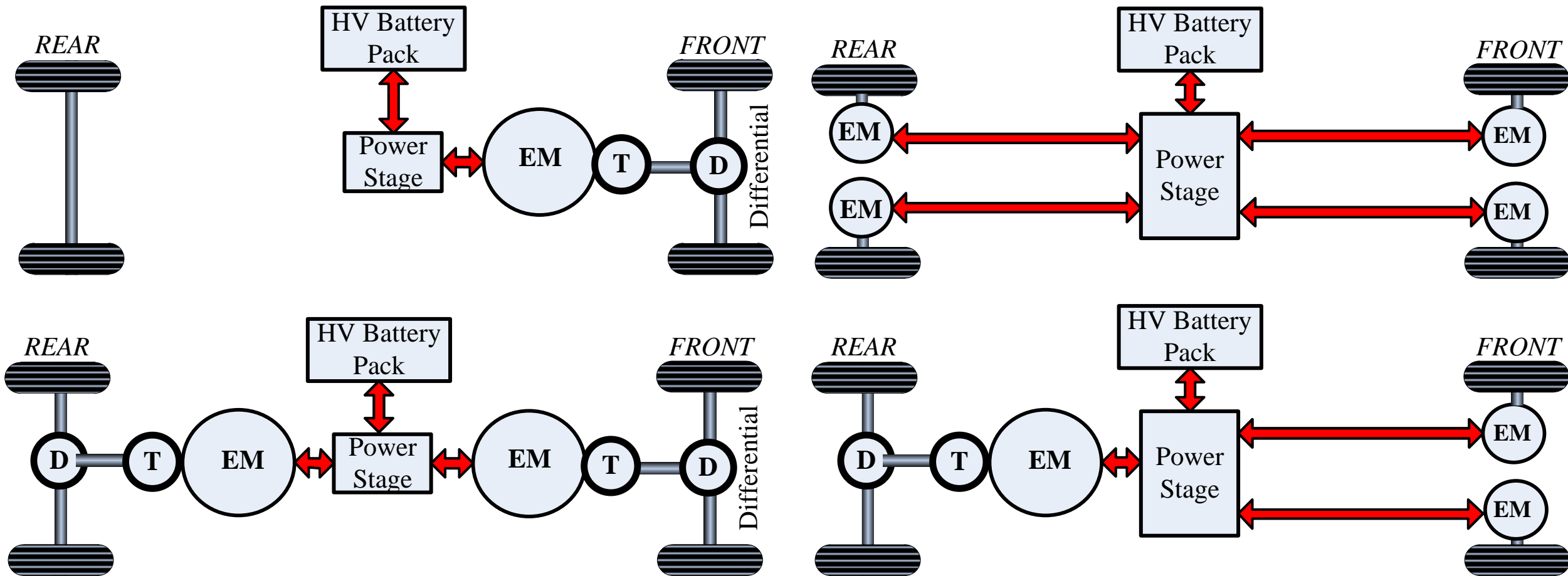


Introduction



Electric Powertrains for Heavy-Duty Applications

- Heavy duty electric powertrains are complex systems
- A variety of architectures can be used



Electric Powertrains for Heavy-Duty Applications

➤ Challenges

- Reducing development time
- Dealing with various temperature levels
- Reducing cost
- Reducing losses
- Minimizing failure rate
- Increasing power density
- Optimizing power per unit weight

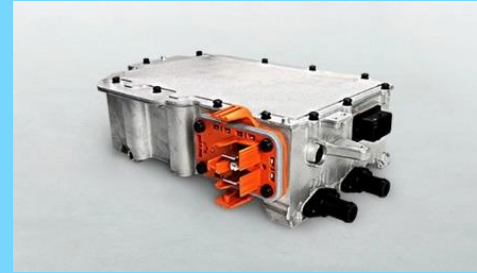
➤ HOW can we tackle these challenges?

- Through modeling and simulation



Addressing Challenges Through Modeling and Simulation

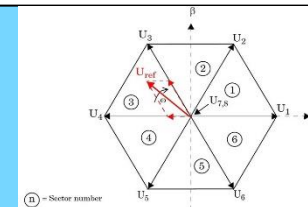
PHYSICAL SYSTEM



Abstraction

MATHEMATICAL MODEL

Goal: the simplest possible model that incorporates the major features of the real system



$$\frac{d\omega_r}{dt} = \frac{1}{H} (T_{em} - b\omega_r - J_0 - T_{load}) \quad (1)$$

$$\text{If } \begin{aligned} T_{load} &= 0 \\ T_{em} &= 0 \end{aligned}$$

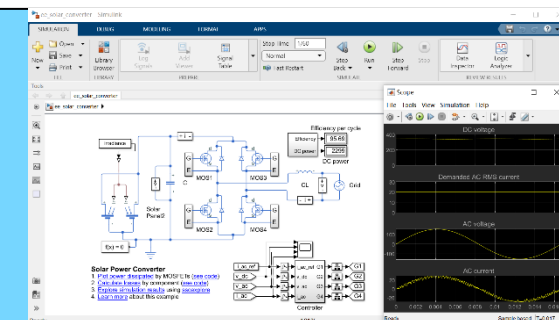
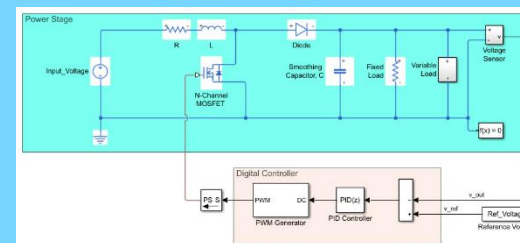
$$\text{Then } \omega_r = \left(\omega_{r0} + \frac{J_0}{b} \right) e^{-\frac{b}{H}t} - \frac{J_0}{b} \quad (2)$$

computer language,
Discretization

SIMULATION MODEL

Desktop simulation

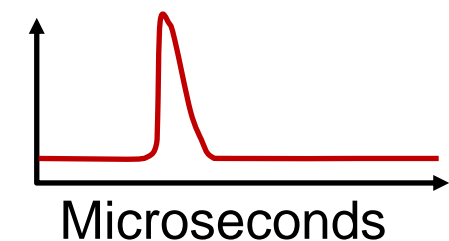
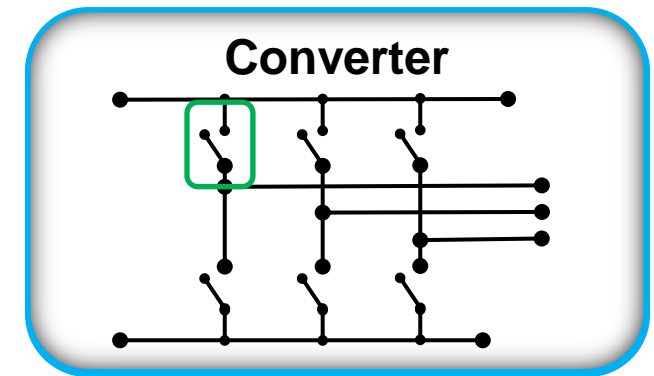
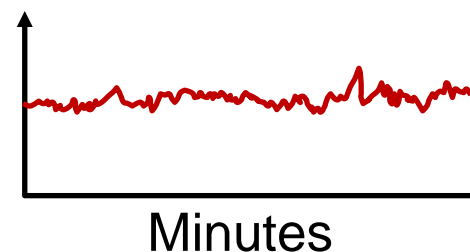
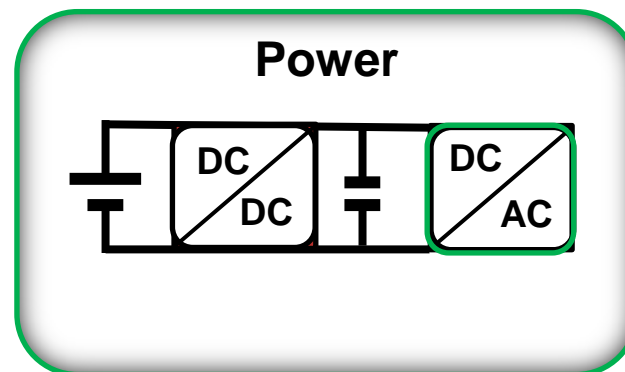
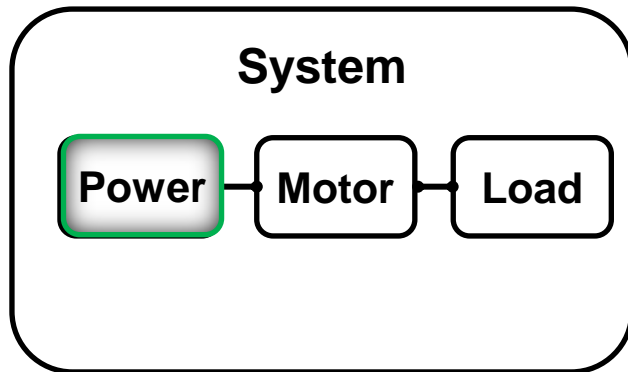
Real-time simulation



Addressing Challenges Through Modeling and Simulation

- The **Simscape™ Electrical™** library provides a range of fidelity levels for users to design with

System-level	Component Validation	Component Design
Determine power requirements Evaluate system-level response Measure efficiency	Stay within design envelope Effect of switching dynamics	Losses during switching events Analyze & predict fault behavior



Parameterization workflows for Semiconductor Devices

- Parameterize from a datasheet
- Parameterize from a datasheet (using physics model)
- Parameterize from a datasheet (using tabulation)
- Import parameters from XML file
- Import from SPICE

Block Parameters: N-Channel MOSFET

N-Channel MOSFET

This block represents a three-terminal or four-terminal N-channel metal-oxide-semiconductor (MOSFET) or an insulated-gate field effect transistor (IGFET) voltage or a surface-potential model, in your model, right-click the block icon, and then select the MOSFET model.

Settings

Main Ohmic Resistance Capacitance Body Diode Temperature

Number of terminals: Three

Parameterization: Specify from: Datasheet

Drain-source on resistance, $R_{DS(on)}$: 0.025

Drain current, I_{DS} , for $R_{DS(on)}$: 6.0

Gate-source voltage, V_{GS} , for $R_{DS(on)}$: 10

Gate-source threshold voltage, V_{th} : 1.7

Channel modulation, L : 0

Measurement temperature: 25

Electrical Characteristics ($T_J = 25^\circ\text{C}$ unless otherwise noted)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
BV_{DSS}	Drain-Source Breakdown Voltage	$V_{GS} = 0\text{ V}, I_D = 250\ \mu\text{A}$	30			V
I_{DSS}	Zero Gate Voltage Drain Current	$V_{GS} = 24\text{ V}, V_{DS} = 0\text{ V}$		1	20	μA
I_{GSSF}	Gate-Body Leakage, Forward	$V_{GS} = 20\text{ V}, V_{DS} = 0\text{ V}$			100	nA
I_{GBSR}	Gate-Body Leakage, Reverse	$V_{GS} = -20\text{ V}, V_{DS} = 0\text{ V}$			-100	nA
$V_{GS(th)}$	Gate-Source Threshold Voltage	$V_{GS} = V_{DS}, I_D = 250\ \mu\text{A}$		1.7	3	V
$R_{DS(on)}$	Static Drain-Source On-Resistance	$V_{GS} = 10\text{ V}, I_D = 6\text{ A}$	0.025	0.035		Ω
$r_{DS(on)}$	Forward Transconductance	$V_{GS} = 10\text{ V}, I_D = 6\text{ A}$		0.043	0.055	S
C_{iss}	On-State Drain-Source Capacitance	$V_{GS} = 10\text{ V}, I_D = 6\text{ A}$	15			A
C_{oss}	Input Capacitance	$V_{GS} = 15\text{ V}, V_{DS} = 0\text{ V}, f = 1.0\text{ MHz}$		350		pF
C_{out}	Output Capacitance	$V_{GS} = 15\text{ V}, V_{DS} = 0\text{ V}, f = 1.0\text{ MHz}$		220		pF
r_{sw}	Reverse Transfer Resistance	$V_{GS} = 15\text{ V}, I_D = 6\text{ A}, V_{DS} = 10\text{ V}$		80		pF
t_{on}	Total Turn-On Delay Time	$V_{GS} = 15\text{ V}, I_D = 6\text{ A}, V_{DS} = 10\text{ V}$	12	17		nS
$t_{turn-on}$	Turn-On Delay Time	$V_{GS} = 10\text{ V}, I_D = 1\text{ A}$	7.5	15		ns
$t_{turn-on-r}$	Turn-On Rise Time	$V_{GS} = 10\text{ V}, I_D = 1\text{ A}$		12	25	ns
$t_{turn-off}$	Turn-Off Delay Time	$V_{GS} = 4.5\text{ V}, R_{\theta JC} = 6\ \Omega$		13	25	ns
$t_{turn-off-f}$	Turn-Off Fall Time	$V_{GS} = 4.5\text{ V}, R_{\theta JC} = 6\ \Omega$		6	15	ns

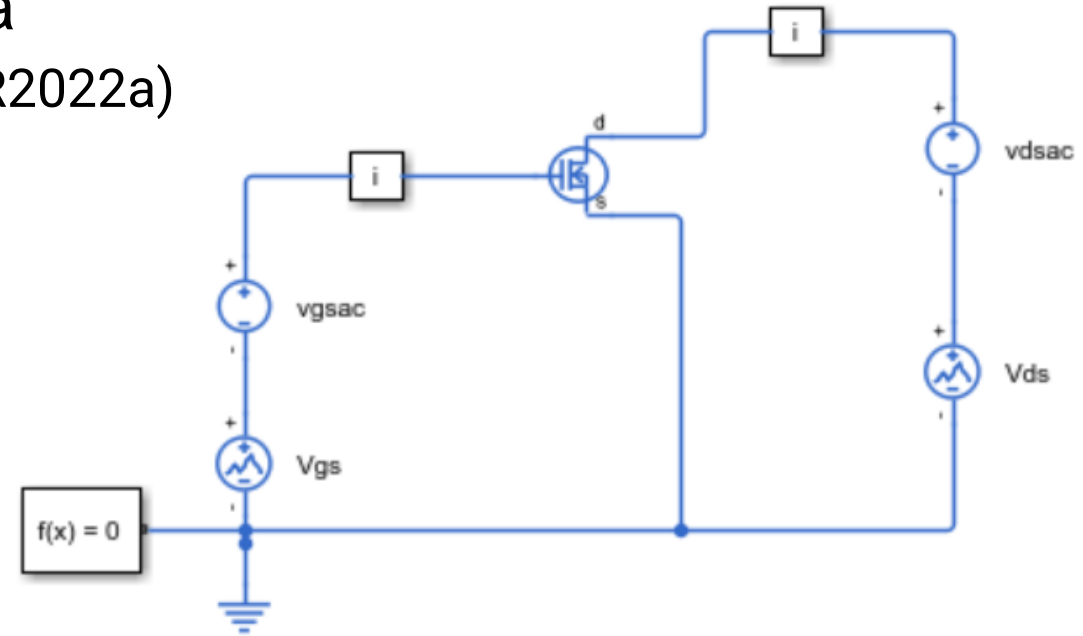
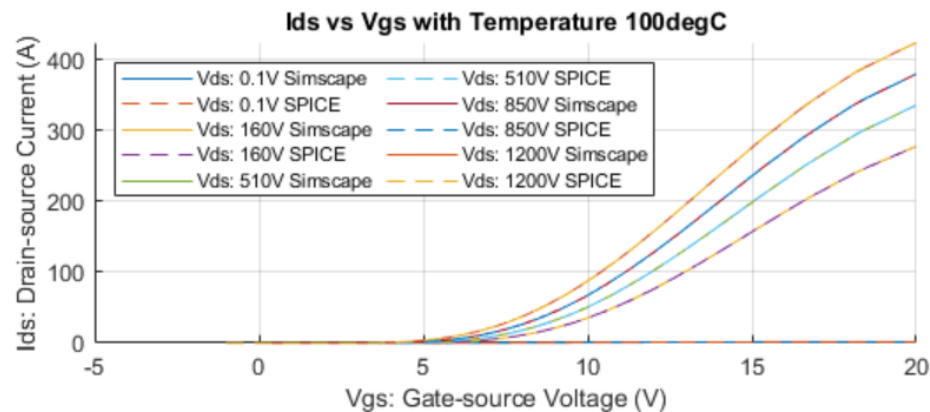
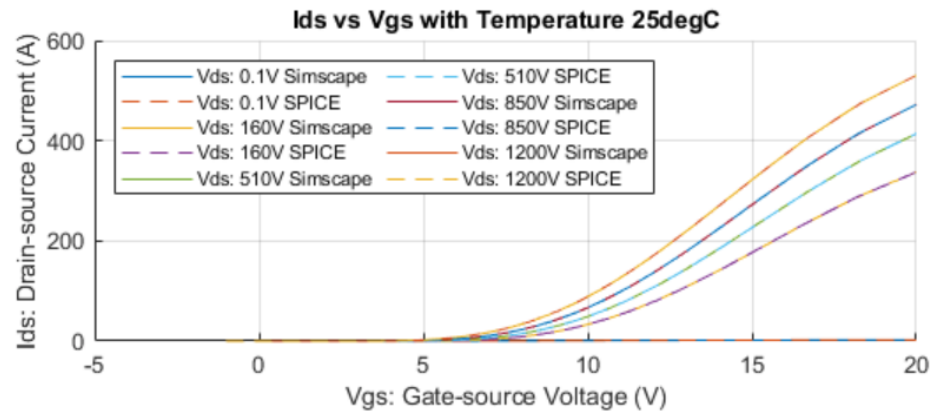
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1 <?xml version="1.0" encoding="UTF-8"?>
2 <SemiconductorLibrary>
3   <Package class="IGBT" vendor="ABB" partnumber="5SNA 1000G650300">
4     <Variables/>
5     <SemiconductorData type="IGBT">
6       <TurnOnLoss>
7         <ComputationMethod>Table only</ComputationMethod>
8         <CurrentAxis> 0 0.1 100 200 300 400 500 600 700 800 900
9         <VoltageAxis> 0 3600</VoltageAxis>
10        <TemperatureAxis> 25 125 150</TemperatureAxis>
11        <Energy scale="1">
12          <Temperature>
13            <Voltage> 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
14            <Voltage> 0 0.15945978 0.56427834 0.97065870000
15          </Temperature>

```

Parameterization workflows for Semiconductor Devices

- Uses LTSPICE to generate the TLU data
 - `ee.spice.semiconductorSubcircuit2lookup` (R2022a)
 - `ee.spice.diodeSubcircuit2lookup` (R2023a)



SiC MOSFET Parameterization Using Simulation Results from SPICE

1. SPICE subcircuit (see SPICE netlist)
2. Set lookup table parameters (see code)
3. Compare results with SPICE (see code)
4. Explore simulation results using Simscape Results Explorer
5. Learn more about this example

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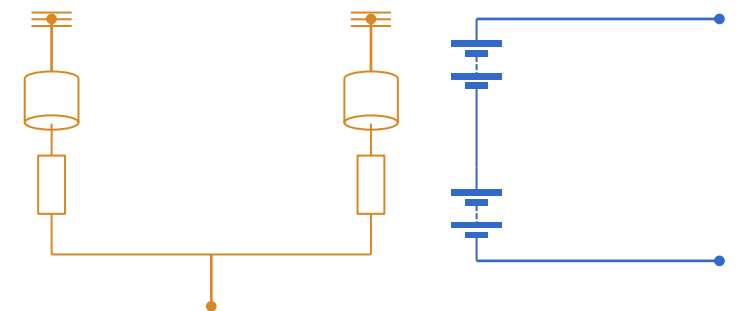
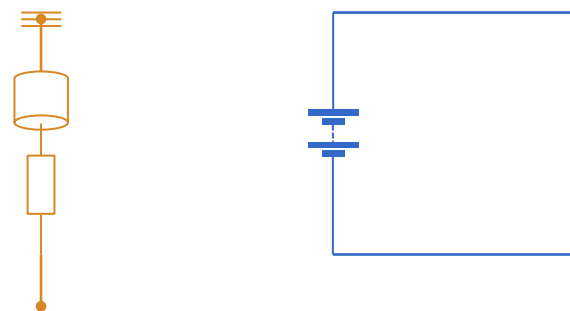
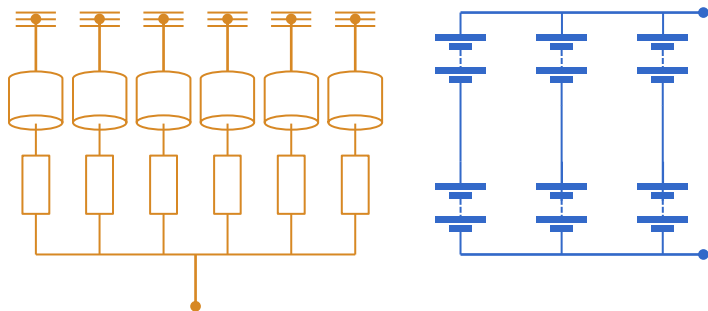
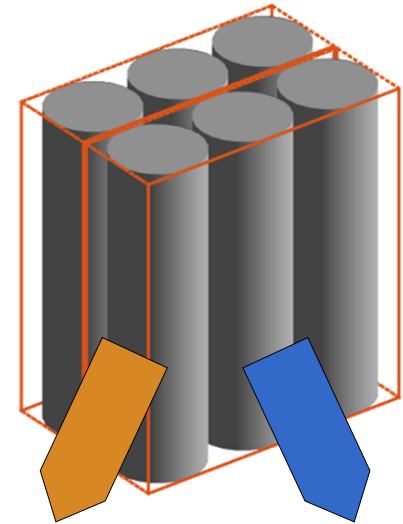
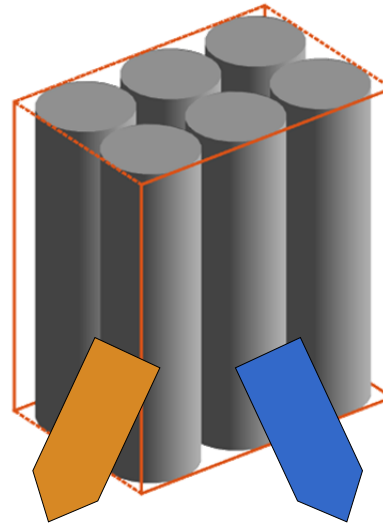
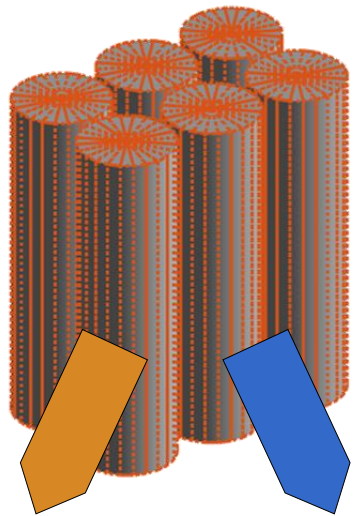
Battery pack model fidelity

Find tradeoff between calculation speed and precision

Detailed module

Lumped module

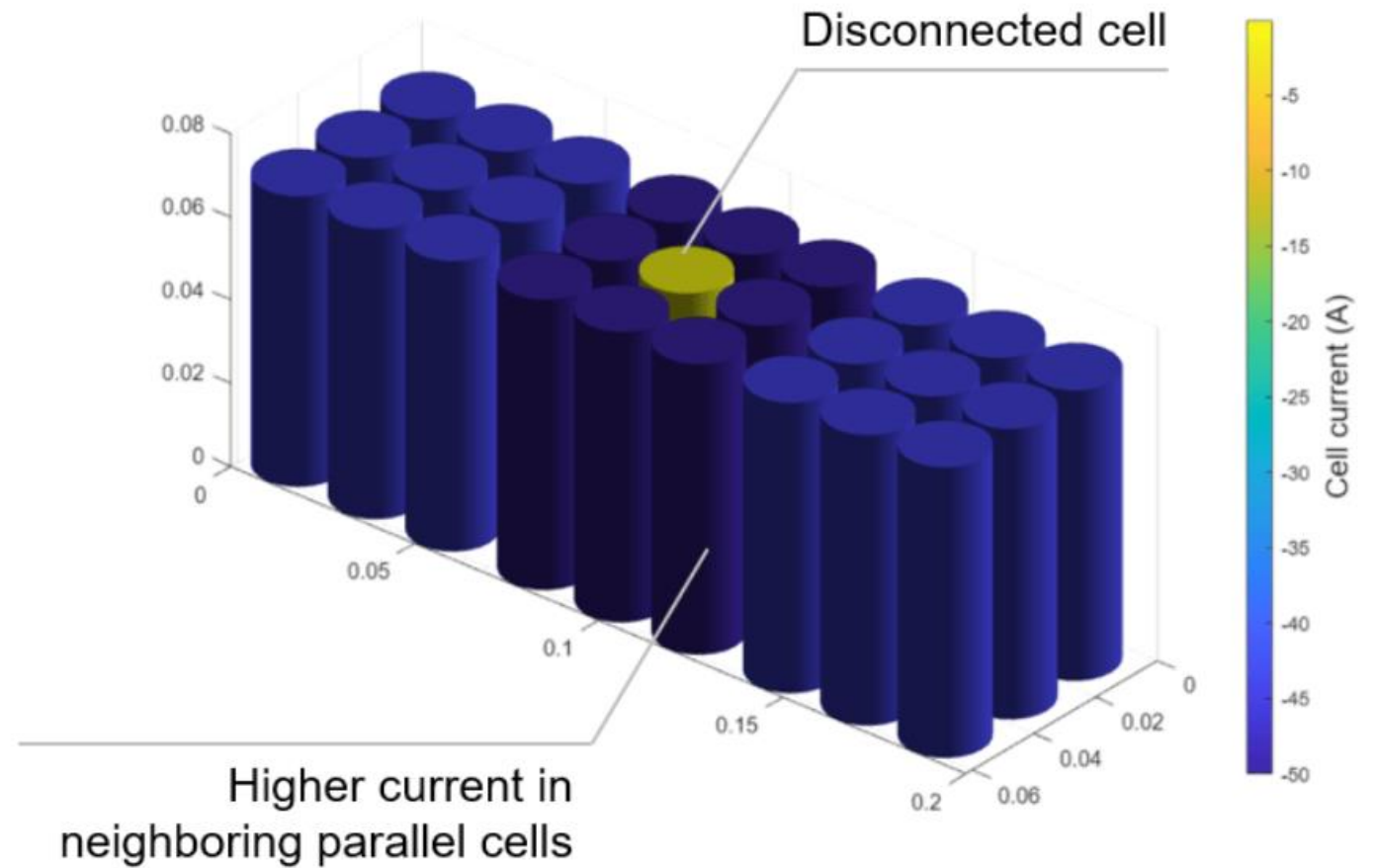
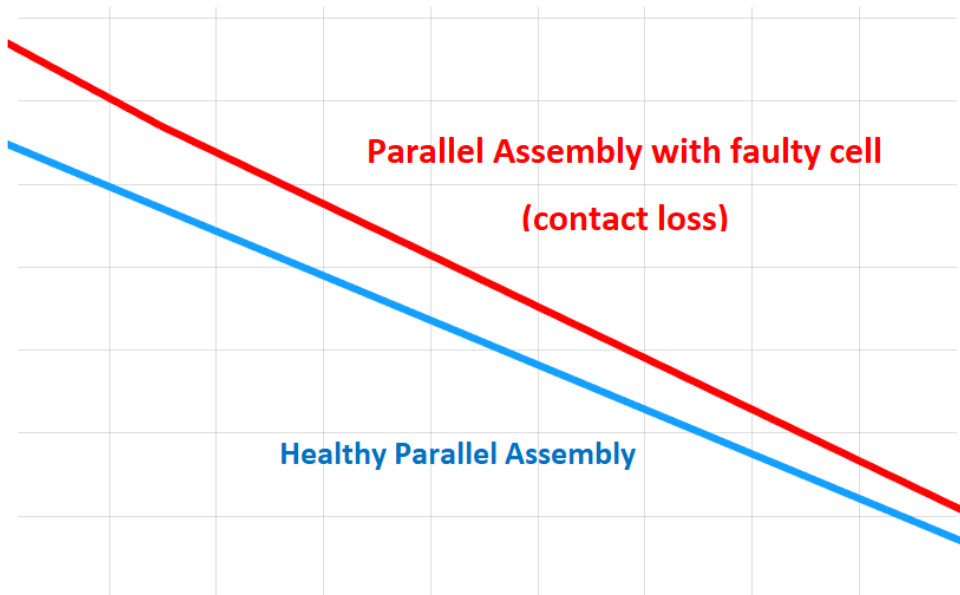
Grouped module



Battery pack model fidelity

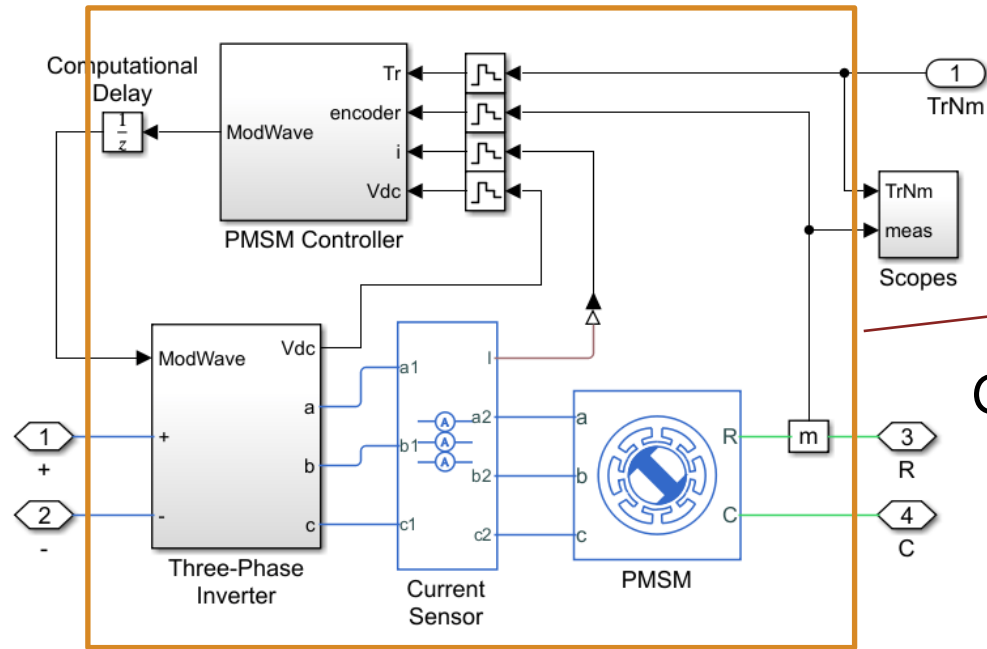
Inject Faults

If one cell loses contact in a parallel assembly, the overall voltage is minimally affected

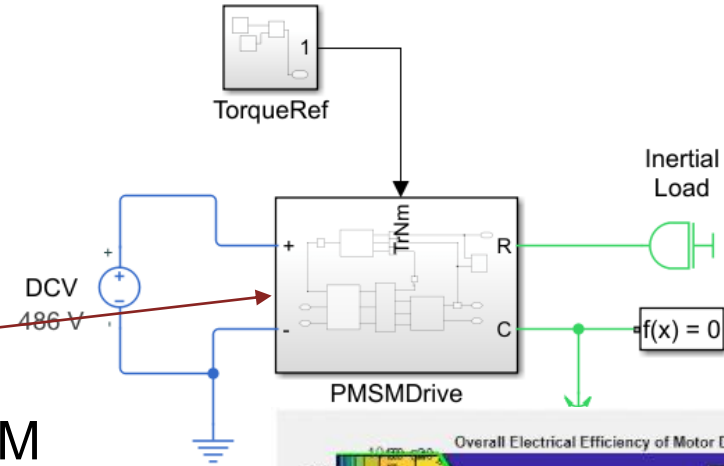


<https://www.mathworks.com/help/simscape-battery/ug/detect-disconnected-cells-example.html>

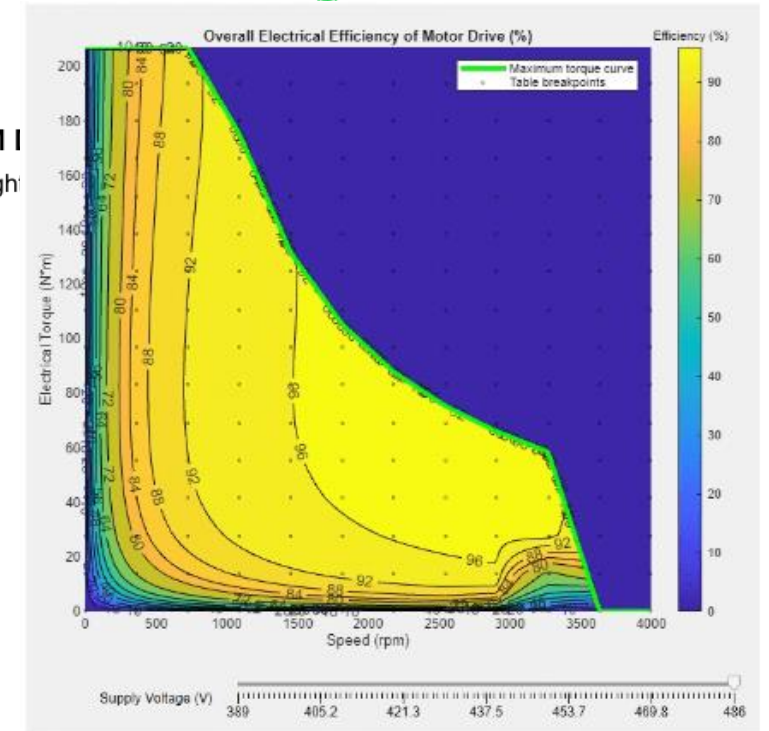
Generate reduced order model for motor



Generate ROM



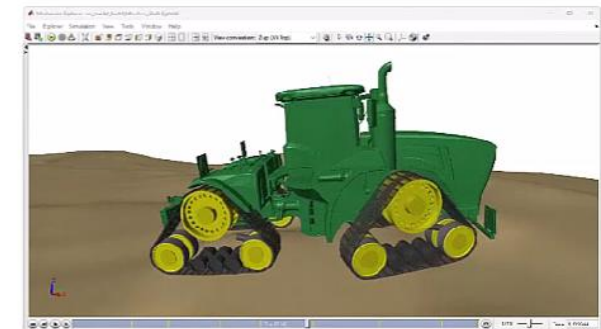
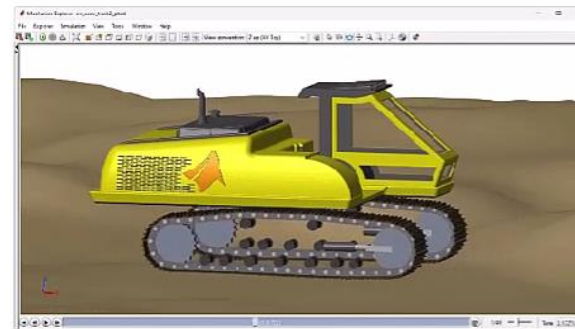
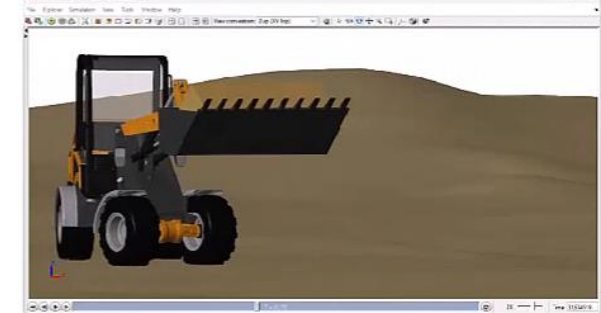
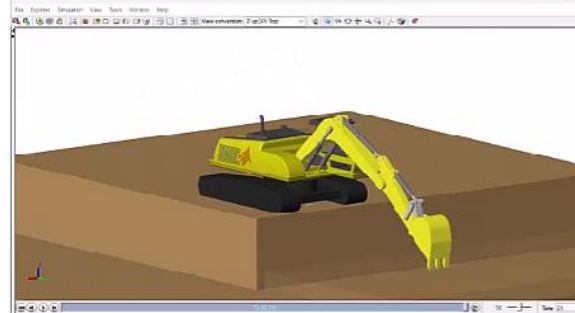
PMSM I
Copyright



Multidomain Simulation

- Tailor Simscape models to your exact design
- Include hydraulics and multibody

Heavy Equipment Design with Simscape



Key Takeaways

- Simulation can play a key role in understanding and optimizing **electric powertrains**
- Selecting an appropriate **fidelity level** and effective **parameterization** is crucial when developing simulation models
- **Simscape Electrical** and **Simscape Battery** offer a framework for simulating electrical systems with a variety of different levels of fidelity
- **Simscape** enables **multidomain simulation**